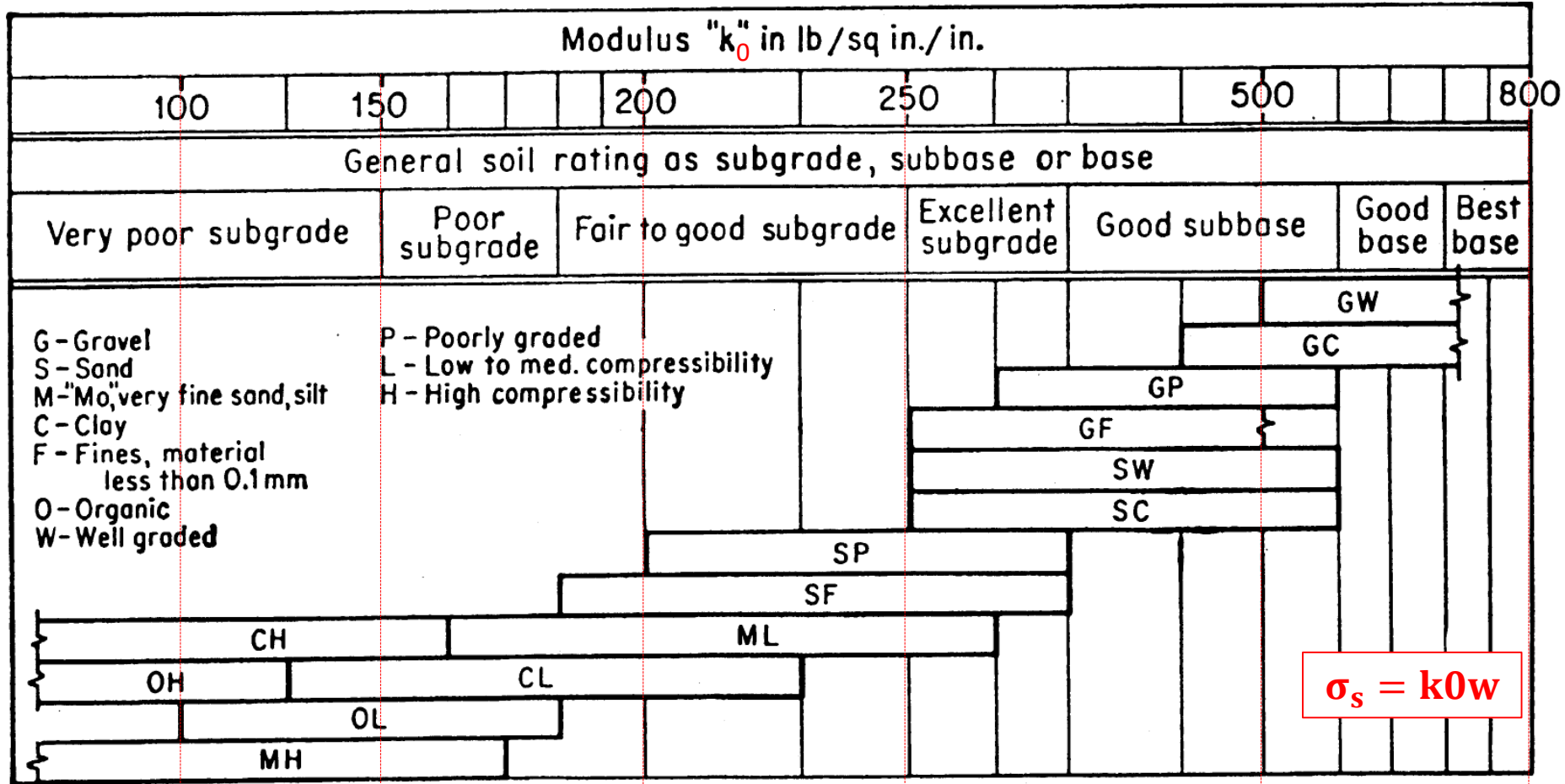


Plates on elastic foundation

Circular elastic plate, axial-symmetric load, Winkler soil
(after *Timoshenko & Woinowsky-Krieger* (1959) - Chapter 8)

Introduction

Winkler model: modulus of subgrade



N/mm ³	0.0271	0.0407	0.0543	0.0679	0.136
kg _f /cm ³	2.76	4.15	5.53	6.92	13.83

Introduction

Circular elastic (thin) plates

The *Kirchhoff–Love theory* of plates is a two-dimensional mathematical model that is used to determine the stresses and deformations in thin plates subjected to forces and moments.

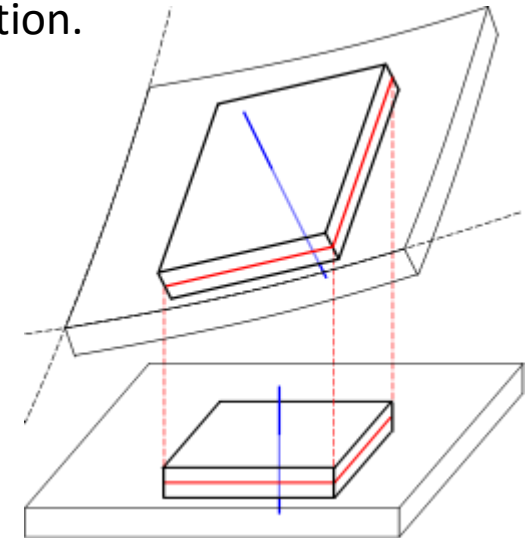
The following *kinematic assumptions* that are made in this theory:

- straight lines normal to the mid-surface remain straight after deformation
- straight lines normal to the mid-surface remain normal to the mid-surface after deformation
- the thickness of the plate does not change during a deformation.

(after *Wikipedia*)

Germain-Lagrange equation (cartesian coordinates)

$$\frac{\partial^4 w}{\partial x^4} + 2 \frac{\partial^4 w}{\partial x^2 \partial y^2} + \frac{\partial^4 w}{\partial y^4} = \frac{q}{D}$$



Introduction

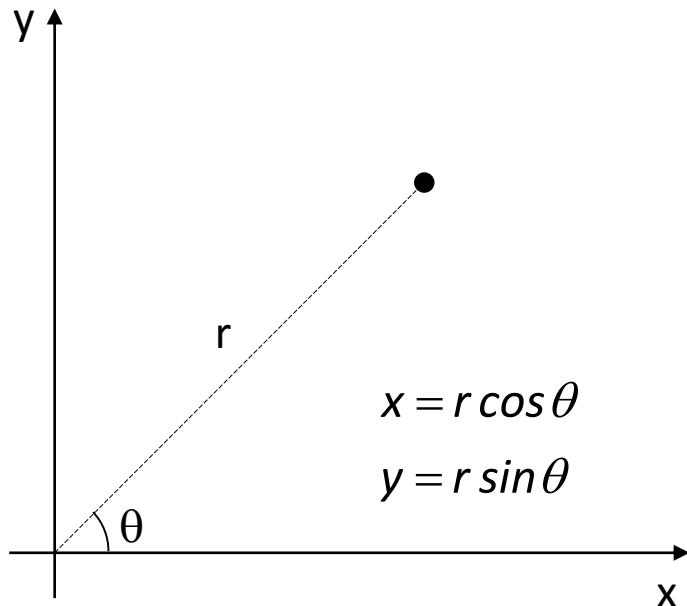
Circular elastic (thin) plates

Germain-Lagrange equation (cartesian coordinates)

$$\Delta_2 w = \Delta \Delta w = \frac{q}{D}$$

$$\Delta(\bullet) = \frac{\partial^2(\bullet)}{\partial x^2} + \frac{\partial^2(\bullet)}{\partial y^2}$$

Conversion to polar (cylindrical) coordinates



$$\frac{\partial w}{\partial x} = \frac{\partial w}{\partial r} \cdot \cos \theta - \frac{1}{r} \cdot \frac{\partial w}{\partial \theta} \cdot \sin \theta$$

$$\frac{\partial w}{\partial y} = \frac{\partial w}{\partial r} \cdot \sin \theta + \frac{1}{r} \cdot \frac{\partial w}{\partial \theta} \cdot \cos \theta$$

$$\Delta(\bullet) = \frac{\partial^2(\bullet)}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial(\bullet)}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2(\bullet)}{\partial \theta^2}$$

Introduction

Circular elastic (thin) plates under axial-symmetric load

Germain-Lagrange equation (polar coordinates)

$$\Delta_2 w = \Delta \Delta w = \frac{q}{D} \quad \Delta(\bullet) = \frac{\partial^2(\bullet)}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial(\bullet)}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2(\bullet)}{\partial^2 \theta}$$

$$\Delta_2 w = \left(\frac{\partial^2(\bullet)}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial(\bullet)}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2(\bullet)}{\partial^2 \theta} \right) \left(\frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial w}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2 w}{\partial^2 \theta} \right) = \frac{q}{D}$$

$$\left(\frac{d^2}{dr^2} + \frac{1}{r} \cdot \frac{d}{dr} \right) \left(\frac{d^2 w}{dr^2} + \frac{1}{r} \cdot \frac{dw}{dr} \right) = \frac{q}{D}$$

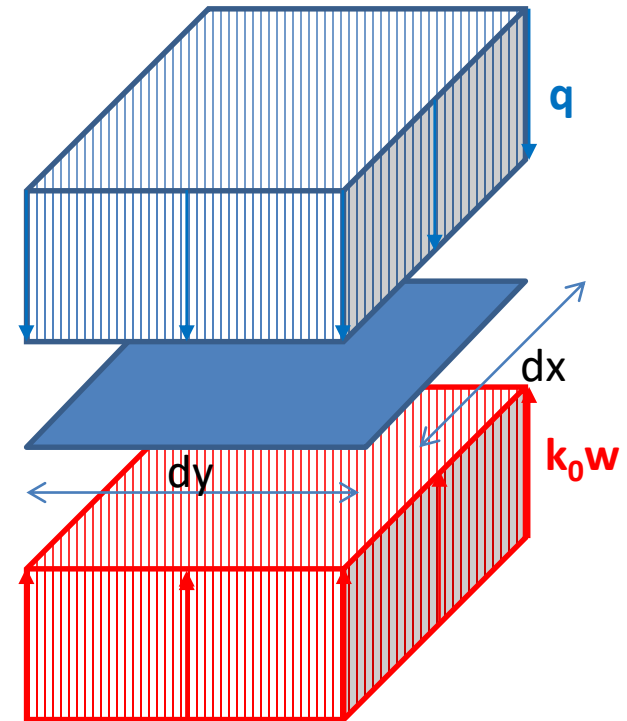
Introduction

Circular elastic (thin) plates on Winkler soil under axial-symmetric load

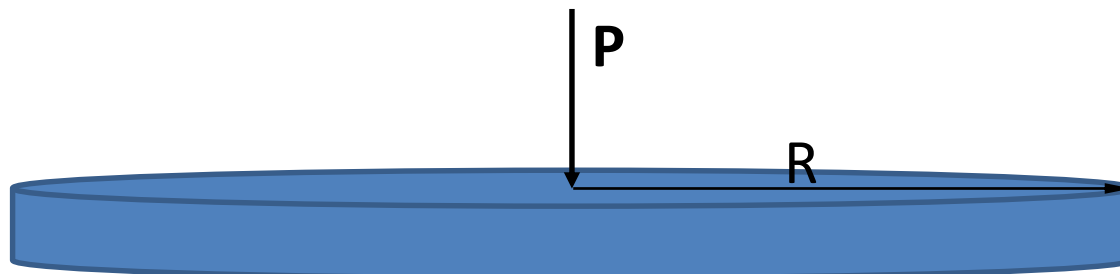
$$\left(\frac{d^2}{dr^2} + \frac{1}{r} \cdot \frac{d}{dr} \right) \left(\frac{d^2 w}{dr^2} + \frac{1}{r} \cdot \frac{dw}{dr} \right) = \frac{q - k_0 w}{D}$$

$$\frac{d^4 w}{dr^4} + \frac{2}{r} \frac{d^3 w}{dr^3} - \frac{1}{r^2} \frac{d^2 w}{dr^2} + \frac{1}{r^3} \frac{dw}{dr} = \frac{q - k_0 w}{D}$$

Since an uniformly distributed load q applied on an elastic plates (or elastic beams) on Winkler soils with uniform k_0 does not determine any stress within the plate, the sole effect of a point load P applied in the centre of the plate is considered hereafter.



$q=0$



Approximate solution

Conversion to a dimensionless form

- Characteristic length:

$$\frac{k_0}{D} = \frac{1}{l^4} \quad \frac{[F][L]^{-3}}{[F][L]} = \frac{1}{[L]^4}$$

- Dimensionless quantities:

Dimensionless displacement $z = \frac{w}{l}$

Dimensionless radius $x = \frac{r}{l}$

Dimensionless derivatives:

$$\frac{dw}{dr} = \frac{l \cdot dz}{l \cdot dx} = \frac{dz}{dx}$$

$$\frac{d^2w}{dr^2} = \frac{d}{dr} \frac{dw}{dr} = \frac{d}{l \cdot dx} \frac{dz}{dx} = \frac{1}{l} \frac{d^2z}{dx^2}$$

$$\frac{d^i w}{dr^i} = \frac{d}{dr} \frac{dw}{dr} = \frac{1}{l^{i-1}} \cdot \frac{d^i w}{dx^i}$$

$$\left(\frac{d^2}{dr^2} + \frac{1}{r} \cdot \frac{d}{dr} \right) \left(\frac{d^2 w}{dr^2} + \frac{1}{r} \cdot \frac{dw}{dr} \right) + \frac{w}{l^4} = 0$$



$$\frac{1}{l^3} \cdot \left(\frac{d^2}{dx^2} + \frac{1}{x} \cdot \frac{d}{dx} \right) \left(\frac{d^2 z}{dx^2} + \frac{1}{x} \cdot \frac{dz}{dx} \right) + \frac{z}{l^3} = 0$$

$$\left(\frac{d^2}{dx^2} + \frac{1}{x} \cdot \frac{d}{dx} \right) \left(\frac{d^2 z}{dx^2} + \frac{1}{x} \cdot \frac{dz}{dx} \right) + z = 0$$

$$\frac{d^4 z}{dx^4} + \frac{2}{x} \frac{d^3 z}{dx^3} - \frac{1}{x^2} \frac{d^2 z}{dx^2} + \frac{1}{x^3} \frac{dz}{dx} + z = 0$$

Approximate solution

General solution

The proposed mathematical transformations led to the following homogeneous 4th-order linear differential equation with variable coefficients:

$$\frac{d^4 z}{dx^4} + \frac{2}{x^3} \frac{d^3 z}{dx^3} - \frac{1}{x^2} \frac{d^2 z}{dx^2} + \frac{1}{x^3} \frac{dz}{dx} + z = 0$$

Therefore, in principle the *general solution* of this differential equation might be written as follows:

$$z = A_1 \cdot X_1(x) + A_2 \cdot X_2(x) + A_3 \cdot X_3(x) + A_4 \cdot X_4(x)$$

where X_i are four independent solutions of the differential equation under consideration and A_i are four integration constants depending on the actual boundary conditions.

Note:

$$\left(\frac{d^2}{dx^2} + \frac{1}{x} \cdot \frac{d}{dx} \right) \left(\frac{d^2 X_i}{dx^2} + \frac{1}{x} \cdot \frac{dX_i}{dx} \right) + X_i = 0 \quad i = 1..4$$

Approximate solution

Approximation by power series

Since X_i are unknown (as the differential equation under consideration includes *variable coefficients*), an approximation based on power series may be firstly assumed. Hence, the general expression of X_i can be taken as follows:

$$X_i = \sum_{n=0}^{N_T} a_n x^n = a_0 + a_1 x^1 + a_2 x^2 + \dots + a_n x^n + \dots + a_{N_T} x^{N_T}$$

where N_T is the highest monomial in the series.

Since X_i should be a solution of the general differential equation, the 2nd order laplacian of each term $a_n x^n$ should find a similar monomial such that:

$$\Delta \Delta X_i + X_i = 0$$

$$\Delta \Delta a_n x^n = \left(\frac{d^2}{dx^2} + \frac{1}{x} \cdot \frac{d}{dx} \right) \left(\frac{d^2 a_n x^n}{dx^2} + \frac{1}{x} \cdot \frac{d a_n x^n}{dx} \right)$$



$$n^2 (n-2)^2 a_n x^{n-4} + a_{n-4} x^{n-4} = 0$$



$$a_n = - \frac{a_{n-4}}{n^2 (n-2)^2}$$

Recursive definition of a_n

$$\frac{d^2 a_n x^n}{dx^2} + \frac{1}{x} \cdot \frac{d a_n x^n}{dx} = n(n-1) a_n x^{n-2} + n a_n x^{n-2} = n^2 a_n x^{n-2}$$

$$\left(\frac{d^2}{dx^2} + \frac{1}{x} \cdot \frac{d}{dx} \right) n^2 a_n x^{n-2} = n^2 (n-2)(n-3) a_n x^{n-4} + n^2 (n-2) a_n x^{n-4} = n^2 (n-2)^2 a_n x^{n-4}$$

Approximate solution

Approximation by power series: first independent solution X_1

$$a_n = -\frac{a_{n-4}}{n^2(n-2)^2} \qquad z = A_1 \cdot X_1(x) + A_2 \cdot X_2(x) + A_3 \cdot X_3(x) + A_4 \cdot X_4(x)$$

Based on the recursive definition of the coefficients, a first independent solution X_1 can be “built up” by assuming a_0 as the first nonzero coefficient:

$$n=0: \quad a_0 = 1 \qquad a_1 = a_2 = a_3 = 0$$

$$n=4: \quad a_4 = -\frac{a_0}{4^2(4-2)^2} = -\frac{1}{4^2 \cdot 2^2}$$

$$n=8: \quad a_8 = -\frac{a_4}{8^2(8-2)^2} = \frac{1}{8^2 \cdot 6^2 \cdot 4^2 \cdot 2^2}$$

$$n=12: \quad a_{12} = -\frac{a_8}{12^2(12-2)^2} = -\frac{1}{12^2 \cdot 10^2 \cdot 8^2 \cdot 6^2 \cdot 4^2 \cdot 2^2}$$

$$X_1(x) = 1 - \frac{1}{64}x^4 + \frac{1}{147456}x^8 - \frac{1}{2123366400}x^{12} \dots$$

Approximate solution

Approximation by power series: second independent solution X_2

$$a_n = -\frac{a_{n-4}}{n^2(n-2)^2}$$

Before proceeding with “constructing” the second independent solution X_2 of z , it should be noted that the assumption of $a_1=1$ is not admissible.

In fact, if one assumes $a_1=1$ (and, at the same time, $a_0=a_2=a_3=0$) the resulting solution X_2 of z would have a first term x :

$$X_2 = x + \dots$$



which implies a nonzero first derivative of X_2 (and, hence, of the general solution z) which cannot be accepted because of the fact that rotations ($\varphi=dX_2/dx=1+\dots$) should be zero at $x=0$.

Therefore, the second solution X_2 should be built by assuming $a_2=1$ and, at the same time, $a_0=a_1=a_3=0$:

$$X_2 = x^2 + \dots$$



this leads to an expression of X_2 whose first nonzero monomial is of 2nd order and, hence, the second derivative of X_2 is non zero ($\chi=d^2X_2/dx_2=1+\dots$): this is acceptable because the curvature is nonzero at the plate centre ($x=0$).

Approximate solution

Approximation by power series: second independent solution X_2

$$a_n = -\frac{a_{n-4}}{n^2(n-2)^2}$$

Based on the recursive definition of the an coefficients, a first independent solution X_2 can be “built up” by assuming a_2 as the first nonzero coefficient:

$$n=2: \quad a_2 = 2 \qquad a_0 = a_1 = a_3 = 0$$

$$n=6: \quad a_6 = -\frac{a_2}{6^2(6-2)^2} = -\frac{1}{6^2 \cdot 4^2}$$

$$n=10: \quad a_{10} = -\frac{a_6}{10^2(10-2)^2} = \frac{1}{10^2 \cdot 8^2 \cdot 6^2 \cdot 4^2}$$

$$n=14: \quad a_{14} = -\frac{a_{10}}{14^2(14-2)^2} = -\frac{1}{14^2 \cdot 12^2 \cdot 10^2 \cdot 8^2 \cdot 6^2 \cdot 4^2}$$

$$X_2(x) = x^2 - \frac{1}{576} x^6 + \frac{1}{3686400} x^{10} - \frac{1}{104044953600} x^{14} \dots$$

Approximate solution

Approximation by power series: third independent solution X_3

$$a_n = -\frac{a_{n-4}}{n^2(n-2)^2}$$

The assumption $a_3=1$ (and, at the same time, $a_0=a_1=a_2=0$) is not even admissible, as it would lead to the a function having the following expression:

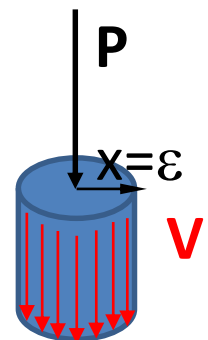
$$X_3 = x^3 + \dots$$



This is not admissible because it would lead to a finite value of shear for $x=0$:

$$V \propto \frac{d}{dx} \left(\frac{d^2 X_3}{dx^2} + \frac{1}{x} \frac{dX_3}{dx} \right) = 2 + \dots$$

whereas shear should be divergent (it should tend to infinity) for $x \rightarrow 0$, as a finite force P should be in equilibrium with shear stresses on an infinitesimal circumference of radius ε .



Approximate solution

Approximation by power series: third independent solution X_3

Since,

on the one hand, shear $V \rightarrow \infty$ for $x \rightarrow 0$,

and

on the other one hand, both X_1 and X_2 would lead to a finite value of shear for $x=0$, the solutions X_3 and X_4 should be capable to reproduce the condition $V \rightarrow \infty$ for $x \rightarrow 0$.

Therefore, a different solution, including the term $\log x$ (which diverges for $x \rightarrow 0$ along with all its derivatives) and an new unknown function F_3 , is preliminarily defined:

$$X_3 = X_1 \cdot \log x + F_3$$

The function X_3 should be, in turn, a solution of the general differential equation:

$$\Delta \Delta X_i + X_i = 0 \quad \longleftrightarrow \quad \left(\frac{d^2}{dx^2} + \frac{1}{x} \cdot \frac{d}{dx} \right) \left(\frac{d^2 X_i}{dx^2} + \frac{1}{x} \cdot \frac{dX_i}{dx} \right) + X_i = 0$$

First of all, the 2nd laplacian of X_3 is determined

$$\Delta \Delta X_3 = \frac{4}{x} \frac{d^3 X_1}{dx^3} + \log x \cdot \Delta \Delta X_1 + \Delta \Delta F_3$$

Approximate solution

Approximation by power series: third independent solution X_3

Then:

$$\Delta\Delta X_3 + X_3 = 0$$

The following condition has to be met:

$$\Delta\Delta X_3 + X_3 = \frac{4}{x} \frac{d^3 X_1}{dx^3} + \log x \cdot \Delta\Delta X_1 + \Delta\Delta F_3 + X_1 \log x + F_3 = 0$$

and, after collecting the term $\log x$,

$$\frac{4}{x} \frac{d^3 X_1}{dx^3} + \log x \cdot (\Delta\Delta X_1 + X_1) + \Delta\Delta F_3 + F_3 = 0$$

the following relationship is derived for F_3 :

$$\Delta\Delta F_3 + F_3 = -\frac{4}{x} \frac{d^3 X_1}{dx^3}$$

$$\Delta\Delta F_3 + F_3 = -4 \cdot \left(-\frac{2 \cdot 3 \cdot 4}{64} + \frac{6 \cdot 7 \cdot 8}{147456} x^4 - \frac{10 \cdot 11 \cdot 12}{2123366400} x^8 + \dots \right)$$

Approximate solution

Approximation by power series: third independent solution X_3

$$\Delta\Delta F_3 + F_3 = -4 \cdot \left(-\frac{2 \cdot 3 \cdot 4}{4^2 \cdot 2^2} + \frac{6 \cdot 7 \cdot 8}{8^2 \cdot 6^2 \cdot 4^2 \cdot 2^2} x^4 - \frac{10 \cdot 11 \cdot 12}{12^2 \cdot 10^2 \cdot 8^2 \cdot 6^2 \cdot 4^2 \cdot 2^2} x^8 + \dots \right)$$

$$\Delta\Delta F_3 + F_3 = 4 \cdot \sum_{n=4}^{n_r} (-1)^{\frac{n}{4}-1} \cdot \frac{n \cdot (n-1) \cdot (n-2)}{n^2 \cdot (n-2)^2 \cdot \dots \cdot 2^2} x^{n-4}$$

The function F_3 may also be approximated by the following power series:

$$F_3 = b_4 x^4 + b_8 x^8 + b_{12} x^{12} + \dots$$

whose 2nd laplacian can be expressed as follows:

$$\Delta\Delta b_n x^n = n^2 (n-2)^2 b_n x^{n-4}$$

$$n^2 (n-2)^2 b_n x^{n-4} + b_{n-4} x^{n-4} = (-1)^{\frac{n}{4}-1} \cdot \frac{n \cdot (n-1) \cdot (n-2)}{n^2 \cdot (n-2)^2 \cdot \dots \cdot 2^2} \cdot x^{n-4} \quad \forall n$$

$$b_n = \frac{1}{n^2 (n-2)^2} \left[-b_{n-4} + (-1)^{\frac{n}{4}-1} \cdot 4 \cdot \frac{n \cdot (n-1) \cdot (n-2)}{n^2 \cdot (n-2)^2 \cdot \dots \cdot 2^2} \right]$$

Approximate solution

Approximation by power series: third independent solution X_3

$$b_n = \frac{1}{n^2(n-2)^2} \left[-b_{n-4} + (-1)^{\frac{n}{4}-1} \cdot 4 \cdot \frac{n \cdot (n-1) \cdot (n-2)}{n^2 \cdot (n-2)^2 \dots 2^2} \right]$$

```
In[36]:= ConstsSol3 = Solve[SimEq3 == 0, Constants3] // Flatten
```

```
Out[36]= {b4 -> 3/128, b8 -> -25/1769472, b12 -> 49/42467328000, b16 -> -761/29831769096192000,
b20 -> 7381/34795775473798348800000, b24 -> -86021/106705560166561387590451200000,
b28 -> 1171733/735179114791093315729589954150400000, b32 -> -2436559/1355082144382943199552780203490017280000000,
b36 -> 14274301/11504192098210675095288054193481874061393920000000, b40 -> -11167027/20200256922016517242516675510551596591897829703680000000}
```

```
In[37]:= X3[x] = Expand[FullSimplify[X3[x] /. ConstsSol3]]
```

```
Out[37]= 3 x^4/128 - 25 x^8/1769472 + 49 x^12/42467328000 - 761 x^16/29831769096192000 + 7381 x^20/34795775473798348800000 - 86021 x^24/106705560166561387590451200000 +
1171733 x^28/735179114791093315729589954150400000 - 2436559 x^32/1355082144382943199552780203490017280000000 +
14274301 x^36/11504192098210675095288054193481874061393920000000 - 11167027 x^40/20200256922016517242516675510551596591897829703680000000 +
Log[x] - 1/64 x^4 Log[x] + x^8 Log[x]/147456 - x^12 Log[x]/2123366400 + x^16 Log[x]/106542032486400 - x^20 Log[x]/13807847410237440000 +
x^24 Log[x]/3849406932415634472960000 - x^28 Log[x]/2040124083669367620517232640000 + x^32 Log[x]/1880178355509689199068681601024000000 -
x^36 Log[x]/2816838087944084125503921126295732224000000 + x^40 Log[x]/6508022718386011963564259370193659730329600000000
```

Approximate solution

Approximation by power series: fourth independent solution X_4

A similar procedure leads to defining the fourth independent solution:

$$X_4 = X_2 \cdot \log x + F_4$$

and, similar considerations, can be done in defining F_4 for X_4 is a solution of the general differential equation.

$$F_4 = c_6 x^6 + c_{10} x^{10} + c_{14} x^{14} + \dots$$

```
In[49] := ConstsSol4 = Solve[SimEq4 == 0, Constants4] // Flatten
```

```
Out[49] = {c6 -> 5/3456, c10 -> -77/221184000, c14 -> 223/14566293504000, c18 -> -4609/21747359671123968000,
c22 -> 55991/46313177155625602252800000, c26 -> -785633/2344321156859353685362212864000000,
c30 -> 835397/165415300827995996039157739683840000000, c34 -> -29889983/6657518575353399939402809139746454896640000000,
c38 -> 197698279/78907253601627020478580763713092174187100897280000000, c42 -> -2736977/2969437767536428034649951300051084699008980966440960000000}
```

```
In[50] := X4[x] = Expand[FullSimplify[X4[x] /. ConstsSol4]]
```

```
Out[50] = 5 x^6/3456 - 77 x^10/221184000 + 223 x^14/14566293504000 - 4609 x^18/21747359671123968000 + 55991 x^22/46313177155625602252800000 - 785633 x^26/2344321156859353685362212864000000 +
835397 x^30/165415300827995996039157739683840000000 - 29889983 x^34/6657518575353399939402809139746454896640000000 +
197698279 x^38/78907253601627020478580763713092174187100897280000000 - 2736977 x^42/2969437767536428034649951300051084699008980966440960000000 +
x^2 Log[x] - 1/576 x^6 Log[x] + x^10 Log[x]/3686400 - x^14 Log[x]/104044953600 + x^18 Log[x]/8629904631398400 - x^22 Log[x]/1670749536638730240000 +
x^26 Log[x]/650549771578242225930240000 - x^30 Log[x]/459027918825607714616377344000000 + x^34 Log[x]/543371544742300178530848982695936000000 -
x^38 Log[x]/10168785497478143693069155265927593328640000000 + x^42 Log[x]/2870038018808231275931838382255403941075353600000000
```

Approximate solution

Approximation by power series: fourth independent solution X_4

In[53]:= zSol

$$\begin{aligned}
 \text{Out[53]= A1} & \left(1 - \frac{x^4}{64} + \frac{x^8}{147456} - \frac{x^{12}}{2123366400} + \frac{x^{16}}{106542032486400} - \frac{x^{20}}{13807847410237440000} + \frac{x^{24}}{3849406932415634472960000} - \frac{x^{28}}{2040124083669367620517232640000} + \right. \\
 & \left. \frac{1880178355509689199068681601024000000}{x^{32}} - \frac{2816838087944084125503921126295732224000000}{x^{36}} + \frac{6508022718386011963564259370193659730329600000000}{x^{40}} \right) + \\
 \text{A2} & \left(x^2 - \frac{x^6}{576} + \frac{x^{10}}{3686400} - \frac{x^{14}}{104044953600} + \frac{x^{18}}{8629904631398400} - \frac{x^{22}}{1670749536638730240000} + \frac{x^{26}}{650549771578242225930240000} - \frac{x^{30}}{459027918825607714616377344000000} + \right. \\
 & \left. \frac{543371544742300178530848982695936000000}{x^{34}} - \frac{1016878549747814369306915526592759332864000000}{x^{38}} + \frac{2870038018808231275931838382255403941075353600000000}{x^{42}} \right) + \\
 \text{A3} & \left(\frac{3x^4}{128} - \frac{25x^8}{1769472} + \frac{49x^{12}}{42467328000} - \frac{761x^{16}}{29831769096192000} + \frac{7381x^{20}}{34795775473798348800000} - \frac{86021x^{24}}{106705560166561387590451200000} + \right. \\
 & \frac{735179114791093315729589954150400000}{1171733x^{28}} - \frac{135508214438294319955278020349001728000000}{2436559x^{32}} + \frac{11504192098210675095288054193481874061393920000000}{14274301x^{36}} - \\
 & \frac{20200256922016517242516675510551596591897829703680000000}{x^{20} \text{Log}[x]} + \text{Log}[x] - \frac{1}{64} x^4 \text{Log}[x] + \frac{x^8 \text{Log}[x]}{147456} - \frac{x^{12} \text{Log}[x]}{2123366400} + \frac{x^{16} \text{Log}[x]}{106542032486400} - \\
 & \frac{13807847410237440000}{x^{36} \text{Log}[x]} + \frac{3849406932415634472960000}{x^{40} \text{Log}[x]} - \frac{2040124083669367620517232640000}{x^{32} \text{Log}[x]} + \frac{1880178355509689199068681601024000000}{x^{40} \text{Log}[x]} - \\
 & \left. \frac{2816838087944084125503921126295732224000000}{6508022718386011963564259370193659730329600000000} \right) + \\
 \text{A4} & \left(\frac{5x^6}{3456} - \frac{77x^{10}}{221184000} + \frac{223x^{14}}{14566293504000} - \frac{4609x^{18}}{21747359671123968000} + \frac{55991x^{22}}{46313177155625602252800000} - \frac{785633x^{26}}{234432115685935368536221286400000} + \right. \\
 & \frac{165415300827995996039157739683840000000}{835397x^{30}} - \frac{6657518575353399939402809139746454896640000000}{29889983x^{34}} + \frac{78907253601627020478580763713092174187100897280000000}{197698279x^{38}} - \\
 & \frac{2969437767536428034649951300051084699008980966440960000000}{x^{22} \text{Log}[x]} + x^2 \text{Log}[x] - \frac{1}{576} x^6 \text{Log}[x] + \frac{x^{10} \text{Log}[x]}{3686400} - \frac{x^{14} \text{Log}[x]}{104044953600} + \frac{x^{18} \text{Log}[x]}{8629904631398400} - \\
 & \frac{1670749536638730240000}{x^{38} \text{Log}[x]} + \frac{650549771578242225930240000}{x^{26} \text{Log}[x]} - \frac{459027918825607714616377344000000}{x^{30} \text{Log}[x]} + \frac{543371544742300178530848982695936000000}{x^{34} \text{Log}[x]} - \\
 & \left. \frac{1016878549747814369306915526592759332864000000}{2870038018808231275931838382255403941075353600000000} \right)
 \end{aligned}$$

Approximate solution

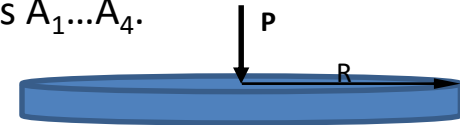
Boundary conditions

The general solution, whose expression was defined by 4th approximate solutions, is reported below:

$$z = A_1 \cdot X_1(x) + A_2 \cdot X_2(x) + A_3 \cdot X_3(x) + A_4 \cdot X_4(x)$$

Four boundary conditions should be written for determining the four constants $A_1 \dots A_4$.

The first two ones are imposed for $r=R$ (namely, for $x=R/l$):



Dimensional expression

$$r = R$$

$$\left[\frac{d^2 w}{dr^2} + \frac{\nu}{r} \frac{dw}{dr} \right]_{r=R} = 0$$

$$\left[\frac{d}{dr} \left(\frac{d^2 w}{dr^2} + \frac{1}{r} \frac{dw}{dr} \right) \right]_{r=R} = 0$$

Dimensionless expression

$$x = R/l$$

$$\left[\frac{d^2 z}{dx^2} + \frac{\nu}{x} \frac{dz}{dx} \right]_{x=\frac{R}{l}} = 0$$

$$\left[\frac{d}{dx} \left(\frac{d^2 z}{dx^2} + \frac{1}{x} \frac{dz}{dx} \right) \right]_{x=\frac{R}{l}} = 0$$

Approximate solution

Boundary conditions

The general solution, whose expression was defined by 4th approximate solutions, is reported below:

$$z = A_1 \cdot X_1(x) + A_2 \cdot X_2(x) + A_3 \cdot X_3(x) + A_4 \cdot X_4(x)$$

Other two boundary conditions are imposed for $r=0$ (namely, for $x=0$):

Dimensional expression

$$r = 0$$

$$\left[\frac{dw}{dr} \right]_{r=R} = 0$$

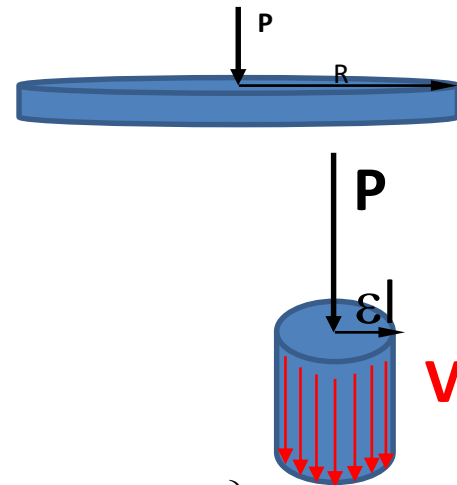
$$\lim_{\varepsilon \rightarrow 0} \left\{ -2\pi\varepsilon l \cdot D \left[\frac{d}{dr} \left(\frac{d^2w}{dr^2} + \frac{1}{r} \frac{dw}{dr} \right) \right]_{r=\varepsilon l} \right\} + P = 0$$

Dimensionless expression

$$x = R/l$$

$$\left[\frac{dz}{dx} \right]_{x=0} = 0$$

$$\lim_{\varepsilon \rightarrow 0} \left\{ -2\pi\varepsilon \cdot k_0 l^3 \left[\frac{d}{dx} \left(\frac{d^2z}{dx^2} + \frac{1}{x} \frac{dz}{dx} \right) \right]_{x=\varepsilon} \right\} + P = 0$$



Approximate solution

Boundary conditions: expressions of constants

First of all, let's consider the third boundary condition:

$$\left[\frac{dz}{dx} \right]_{x=0} = 0$$

Since X_1 and X_2 are polynomials with even order power terms (i.e. $x^0, x^4, x^8 \dots$ and $x^2, x^6, x^{10} \dots$, respectively), their first derivative is zero for $x=0$.

Moreover, the first derivative of X_4 is also zero for $x=0$ (or, better, in the limit of $x \rightarrow 0$):

$$\left[\frac{dX_4}{dx} \right]_{x=0} = \lim_{\varepsilon \rightarrow 0} \left[\frac{d}{dx} (X_2 \log x + F_4) \right]_{x=\varepsilon} = \lim_{\varepsilon \rightarrow 0} \left[2x \cdot \log x + \dots - \frac{x^2}{x} + \dots \right]_{x=\varepsilon} = 0$$

Therefore, the first derivative of z in $x=0$ only takes a nonzero contribution from X_3 :

$$\left[\frac{dz}{dx} \right]_{x=0} = A_3 \cdot \left[\frac{dX_3}{dx} \right]_{x=0} = A_3 \cdot \lim_{\varepsilon \rightarrow 0} \left[\frac{d}{dx} (X_1 \log x + F_3) \right]_{x=\varepsilon} = A_3 \cdot \lim_{\varepsilon \rightarrow 0} \left[-\frac{1}{x} + \dots \right]_{x=\varepsilon} = 0$$

which is only satisfied for $A_3=0$.

Approximate solution

Boundary conditions: expressions of constants

Then, the fourth condition can be considered:

$$\lim_{\varepsilon \rightarrow 0} \left\{ -2\pi\varepsilon \cdot k_0 l^3 \left[\frac{d}{dx} \left(\frac{d^2 z}{dx^2} + \frac{1}{x} \frac{dz}{dx} \right) \right]_{x=\varepsilon} \right\} + P = 0$$

and, once again, no contribution comes from X_1 and X_2 , but the only nonzero terms is given by the third derivatives of X_4 :

$$\begin{aligned} \left[\frac{d}{dx} \left(\frac{d^2 z}{dx^2} + \frac{1}{x} \frac{dz}{dx} \right) \right]_{x=\varepsilon} &= A_4 \cdot \left[\frac{d}{dx} \left(\frac{d^2 X_4}{dx^2} + \frac{1}{x} \frac{dX_4}{dx} \right) \right]_{x=\varepsilon} = A_4 \cdot \left[\frac{d}{dx} \left(\frac{d^2}{dx^2} + \frac{1}{x} \frac{d}{dx} \right) (X_2 \cdot \log x + F_4) \right]_{x=\varepsilon} = \\ &= A_4 \cdot \left[\frac{d}{dx} \left(\frac{d^2}{dx^2} + \frac{1}{x} \frac{d}{dx} \right) (X_2 \cdot \log x + F_4) \right]_{x=\varepsilon} = A_4 \cdot \left[\frac{d}{dx} \left(\frac{d^2}{dx^2} + \frac{1}{x} \frac{d}{dx} \right) (x^2 \cdot \log x + \dots) \right]_{x=\varepsilon} = \\ &A_4 \cdot \left[\frac{2}{x} + \frac{2}{x} \right]_{x=\varepsilon} = \boxed{A_4 \cdot \frac{4}{\varepsilon}} \end{aligned}$$

Therefore:

$$\lim_{\varepsilon \rightarrow 0} \left\{ -2\pi\varepsilon \cdot k_0 l^3 \cdot \boxed{A_4 \cdot \frac{4}{\varepsilon}} \right\} + P = 0 \quad \rightarrow \quad -8\pi \cdot k_0 l^3 \cdot A_4 + P = 0 \quad \rightarrow \quad \bar{A}_4 = \frac{P}{8\pi k_0 l^3}$$

Approximate solution

Boundary conditions: expressions of constants

Finally, the first two equations can be considered for determining the two constants A_1 and A_2 :

$$\left[\frac{d^2 z}{dx^2} + \frac{\nu}{x} \frac{dz}{dx} \right]_{x=\frac{R}{l}} = 0 \qquad \left[\frac{d}{dx} \left(\frac{d^2 z}{dx^2} + \frac{1}{x} \frac{dz}{dx} \right) \right]_{x=\frac{R}{l}} = 0$$

$$\bar{z}(x) = \bar{A}_1 \cdot X_1(x) + \bar{A}_2 \cdot X_2(x) + \bar{A}_4 \cdot X_4(x)$$

$$\bar{w}(r) = l \cdot \bar{z} \left(\frac{r}{l} \right)$$

$$\bar{M}_r(r) = -D \left(\frac{d^2 \bar{w}}{dr^2} + \frac{\nu}{r} \frac{d\bar{w}}{dr} \right)$$

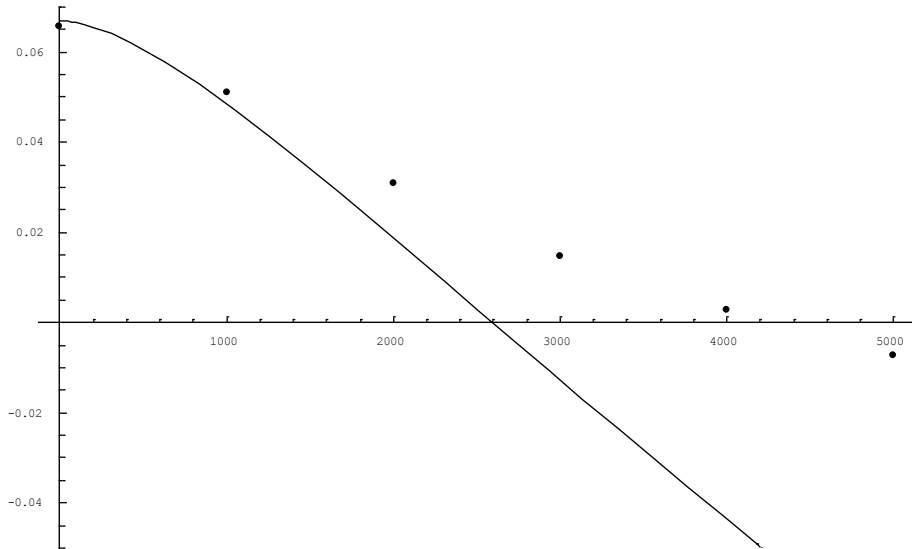
$$\bar{M}_\theta(r) = -D \left(\frac{1}{r} \frac{d\bar{w}}{dr} + \nu \cdot \frac{d^2 \bar{w}}{dr^2} \right)$$

$$\bar{V}_r(r) = -D \left[\frac{d}{dr} \left(\frac{d^2 \bar{w}}{dr^2} + \frac{1}{r} \frac{d\bar{w}}{dr} \right) \right]$$

Approximate solution

Comparisons: proposed procedure vs FEM solution

$N_T=4$



$N_T=12$

